

# SHIFTING PROPERTIES OF FINITE COSINE HYPERBOLIC TRANSFORMS

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## ABSTRACT

A RAM Finite Hyperbolic Transforms are defined in [1]. Moreover these transforms of some standard functions are obtained in the same paper. In this paper we proved some shifting properties of RAM finite cosine hyperbolic transform.

**Keywords:** Generalized Transform, Finite transform, Finite hyperbolic transform, properties of finite transforms.

## 1. INTRODUCTION:

If the disturbance is  $f(t) = e^{at^2}$ , for  $a > 0$ , the usual Laplace transform cannot be used to find the solution of an initial value problem because Laplace transform of  $f(t)$  does not exist. It is often true that the solution at times later than  $t$  would not affect the state at time  $t$ . This leads to define Finite Laplace transform.

The finite Laplace transform of a continuous or an almost piecewise continuous function  $f$  in  $(0, T)$  is denoted by  $L_T(f(t)) = F(p, T)$ , and is defined as

$$L_T(f(t)) = F(p, T) = \int_0^T f(t) e^{-pt} dt \quad (1.1)$$

where  $p$  is a real or complex number and  $T$  be a finite number which may be positive or negative. RAM finite sine and cosine hyperbolic transforms are defined in [1] as follows:

**Definition 1.1 [1]:** Let  $p \in \mathbb{C}$  and  $T$  be a finite number which may be positive or negative and  $f$  is a continuous or an almost piecewise continuous function defined over the interval  $(0, T)$ . Then RAM Finite Sine Hyperbolic transform of  $f$  is denoted by  $Rsh(f(t)) = FS(p, T)$ , and is defined as

$$R_{sh}(f(t)) = F_S(p, T) = \int_0^T \sinh(pt) f(t) dt$$

where  $\sinh(pt)$  is a Kernel of  $Rsh$ .

Here  $Rsh$  is called RAM Finite Sine Hyperbolic transformation operator.

**Definition 1.2 [1]:** Let  $p \in \mathbb{C}$  and  $T$  be a finite number which may be positive or negative and  $f$  is a continuous or an almost piecewise continuous function defined over the interval  $(0, T)$ . Then

RAM Finite Cosine Hyperbolic transform of  $f$  is denoted by  $R_{ch}(f(t)) = F_C(p, T)$ , and defined by

$$R_{ch}(f(t)) = F_C(p, T) = \int_0^T \cosh(pt) f(t) dt$$

where  $\cosh(pt)$  is a Kernel of  $R_{ch}$ .

Here  $R_{ch}$  is called RAM Finite Cosine Hyperbolic transformation operator.

In this paper we obtained some properties of finite hyperbolic cosine transform. Shifting properties are obtained in section [3], examples on these properties are obtained in section [4].

## 2. PRELIMINARIES:

### 2.1 RAM Finite Sine Hyperbolic Transform of some standard functions [1]

$$1 \quad R_{sh}(1) = \frac{\cosh(pT) - 1}{p}$$

$$2 \quad R_{sh}(t) = \frac{T \cosh(pT)}{p} - \frac{\sinh(pT)}{p^2}$$

$$3 \quad R_{sh}(t^2) = \frac{T^2 \cosh(pT)}{p} - \frac{2T \sinh(pT)}{p^2} + \frac{(2 \cosh(pT) - 2)}{p^3}$$

$$4 \quad R_{sh}(t^k) = \begin{cases} \frac{T^k \cosh(pT)}{p} - \frac{kT^{k-1} \sinh(pT)}{p^2} + \dots + \frac{k!(-1)^k [\cosh(pT) - 1]}{p^k}, & \text{if } k \text{ is even} \\ \frac{T^k \cosh(pT)}{p} - \frac{kT^{k-1} \sinh(pT)}{p^2} + \dots + \frac{k!(-1)^k \sinh(pT)}{p^k}, & \text{if } k \text{ is odd} \end{cases}$$

$$5 \quad R_{sh}(\sin(at)) = \left( \frac{-a}{p^2 + a^2} \right) \sinh(pT) \cos(aT) + \left( \frac{p}{p^2 + a^2} \right) \cosh(pT) \sin(aT).$$

$$6 \quad R_{sh}(\cos(at)) = \left( \frac{a}{p^2 + a^2} \right) \sinh(pT) \sin(aT) + \left( \frac{p}{p^2 + a^2} \right) [\cosh(pT) \cos(aT) - 1].$$

$$7 \quad R_{sh}(e^{at}) = \left( \frac{-a}{p^2 - a^2} \right) \sinh(pT) \cdot e^{aT} + \left( \frac{p}{p^2 - a^2} \right) [\cosh(pT) \cdot e^{aT} - 1], \text{ provided } p^2 \neq a^2.$$

$$8 \quad R_{sh}(e^{-at}) = \left( \frac{a}{p^2 - a^2} \right) \sinh(pT) \cdot e^{-aT} + \left( \frac{-p}{p^2 - a^2} \right) [1 - \cosh(pT) \cdot e^{-aT}], \text{ provided } p^2 \neq a^2.$$

### 2.2 RAM Finite Cosine Hyperbolic Transform of some standard functions [1]

$$1 \quad R_{ch}(1) = \frac{\sinh(pT)}{p}.$$

$$2 \quad R_{ch}(t) = \frac{T \sinh(pT)}{p} - \left( \frac{\cosh(pT) - 1}{p^2} \right)$$

$$3 \quad R_{ch}(t^2) = \frac{T^2 \cdot \sinh(pT)}{p} - \frac{2T \cdot \cosh(pT)}{p^2} + \frac{2 \cdot \sinh(pT)}{p^3}.$$

$$4 \quad R_{ch}(t^k) = \begin{cases} \frac{T^k \sinh(pT)}{p} - \frac{kT^{k-1} \cosh(pT)}{p^2} + \dots + \frac{k!(-1)^k \sinh(pT)}{p^k}, & \text{if } k \text{ is even,} \\ \frac{T^k \sinh(pT)}{p} - \frac{kT^{k-1} \cosh(pT)}{p^2} + \dots + \frac{k!(-1)^k [\cosh(pT) - 1]}{p^k}, & \text{if } k \text{ is odd.} \end{cases}$$

$$5 \quad R_{ch}(\sin(at)) = \left( \frac{a}{p^2 + a^2} \right) [1 - \cosh(pT) \cos(aT)] + \left( \frac{p}{p^2 + a^2} \right) \sinh(pT) \sin(aT).$$

$$6 \quad R_{ch}(\cos(at)) = \left( \frac{a}{p^2 + a^2} \right) \cosh(pT) \sin(aT) + \left( \frac{p}{p^2 + a^2} \right) \sinh(pT) \cos(aT).$$

$$7 \quad R_{ch}(e^{at}) = \left( \frac{a}{p^2 - a^2} \right) [\cosh(pT) e^{aT} - 1] + \left( \frac{p}{p^2 - a^2} \right) \sinh(pT) e^{aT}, \text{ provided } p^2 \neq a^2.$$

$$8 \quad R_{ch}(e^{-at}) = \left( \frac{a}{p^2 - a^2} \right) \cosh(pT) e^{-aT} + \left( \frac{-p}{p^2 - a^2} \right) [1 - \sinh(pT) e^{-aT}], \text{ provided } p^2 \neq a^2.$$

### 2.3 Some Properties of RAM Finite Cosine Hyperbolic Transform [1]

1 Linearity:  $R_{ch}(f_1(t) + f_2(t)) = R_{ch}(f_1(t)) + R_{ch}(f_2(t))$

2 Scalar Multiplication: If  $c$  is any constant, then  $R_{ch}(c \cdot f(t)) = c \cdot R_{ch}(f(t))$

3 Scaling: If  $R_{ch}(f(t)) = F_C(p, T)$ , then  $R_{ch}(f(at)) = \frac{F_C\left(\frac{p}{a}, aT\right)}{a}$

## 3. SHIFTING PROPERTIES OF RAM FINITE COSINE HYPERBOLIC TRANSFORM:

**Theorem 3.1:** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(\cosh(at) \cdot f(t)) - R_{sh}(\sinh(at) \cdot f(t)) = F_C((p - a), T)$$

**Proof:** Let  $R_{ch}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$\begin{aligned} R_{ch}(\cosh(at) \cdot f(t)) - R_{sh}(\sinh(at) \cdot f(t)) &= \int_0^T [f(t)(\cosh(at) \cdot \cosh(pt) - \sinh(at) \cdot \sinh(pt))] dt \\ &= \int_0^T f(t) \cosh(p - a)t dt \end{aligned}$$

$$= F_C((p-a), T)$$

**Theorem 3.2:** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{sh}(\sinh(at).f(t)) + R_{ch}(\cosh(at).f(t)) = F_C((p+a), T)$$

**Proof:** Let  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$\begin{aligned} R_{sh}(\sinh(at).f(t)) + R_{ch}(\cosh(at).f(t)) &= \int_0^T [f(t)(\sinh(pt).\sinh(at) + \cosh(at).\cosh(pt))] dt \\ &= \int_0^T f(t)(\cosh(p+a)t) dt \\ &= F_C((p+a), T) \end{aligned}$$

**Theorem 3.3:** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(\cosh(at).f(t)) = \frac{F_C((p+a), T) + F_C((p-a), T)}{2}$$

**Proof:** Using Theorem 3.1 and Theorem 3.2, we have,

$$\begin{aligned} R_{sh}(\sinh(at).f(t)) + R_{ch}(\cosh(at).f(t)) &= F_C((p+a), T) \text{ and} \\ R_{ch}(\cosh(at).f(t)) - R_{sh}(\sinh(at).f(t)) &= F_C((p-a), T) \\ \Rightarrow R_{ch}(\cosh(at).f(t)) &= \frac{F_C((p-a), T) + F_C((p+a), T)}{2} \end{aligned}$$

**Theorem 3.4 :** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(\sinh(at).f(t)) = \frac{-F_S((p-a), T) + F_S((p+a), T)}{2}$$

**Proof:** Using Theorem 3.1 and Theorem 3.2, we have,

$$\begin{aligned} R_{ch}(\sinh(at).f(t)) - R_{sh}(\cosh(at).f(t)) &= -F_S((p-a), T) \text{ and} \\ R_{sh}(\cosh(at).f(t)) + R_{ch}(\sinh(at).f(t)) &= F_S((p+a), T) \\ \Rightarrow R_{ch}(\sinh(at).f(t)) &= \frac{-F_S((p-a), T) + F_S((p+a), T)}{2} \end{aligned}$$

**Theorem 3.5:** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(e^{-at}.f(t)) = \frac{F_C((p-a), T) + F_C((p+a), T) + F_S((p-a), T) - F_S((p+a), T)}{2}$$

**Proof:** Using Theorem 3.3 and Theorem 3.4, we have,

$$\begin{aligned} R_{ch}(\cosh(at).f(t)) &= \frac{F_C((p-a), T) + F_C((p+a), T)}{2} \text{ and} \\ R_{ch}(\sinh(at).f(t)) &= \frac{-F_S((p-a), T) + F_S((p+a), T)}{2} \\ \Rightarrow R_{ch}(e^{-at}.f(t)) &= \frac{F_C((p-a), T) + F_C((p+a), T) + F_S((p-a), T) - F_S((p+a), T)}{2} \end{aligned}$$

**Theorem 3.6:** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(\cos(at).f(t)) = \frac{F_C((p-a),T) + F_C((p+a),T) - F_S((p-a),T) - F_S((p+a),T)}{2}$$

**Proof:** Using Theorem 3.3 and Theorem 3.4, we have,

$$R_{ch}(\cosh(at).f(t)) = \frac{F_C((p-a),T) + F_C((p+a),T)}{2} \text{ and}$$

$$R_{ch}(\sinh(at).f(t)) = \frac{-F_S((p-a),T) + F_S((p+a),T)}{2}$$

$$\Rightarrow R_{ch}(\cos(at).f(t)) = \frac{F_C((p-a),T) + F_C((p+a),T) - F_S((p-a),T) - F_S((p+a),T)}{2}$$

**Theorem 3.7:** If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(\cos(at).f(t)) = \frac{F_C((p+ia),T) + F_C((p-ia),T)}{2}$$

**Proof:** Using Theorem 3.3, we have

$$R_{ch}(\cosh(at).f(t)) = \frac{F_C((p+a),T) + F_C((p-a),T)}{2}$$

$$\Rightarrow R_{ch}(\cosh(iat).f(t)) = \frac{F_C((p+ia),T) + F_C((p-ia),T)}{2}$$

$$\Rightarrow R_{ch}(\cos(at).f(t)) = \frac{F_C((p+ia),T) + F_C((p-ia),T)}{2i}$$

**Theorem 3.8:** If  $R_{ch}(f(t)) = F_S(p, T)$  and  $R_{sh}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(\sin(at).f(t)) = \frac{-F_S((p-ia),T) + F_S((p+ia),T)}{2i}$$

**Proof:** Using Theorem 3.4, we have

$$R_{ch}(\sinh(at).f(t)) = \frac{-F_S((p-a),T) + F_S((p+a),T)}{2}$$

$$\Rightarrow R_{ch}(\sinh(iat).f(t)) = \frac{-F_S((p-ia),T) + F_S((p+ia),T)}{2}$$

$$\Rightarrow R_{ch}(\sin(at).f(t)) = \frac{-F_S((p-ia),T) + F_S((p+ia),T)}{2i}$$

**Theorem 3.9:** Suppose  $f(t) = 0$ , for  $t < 0$ . If  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , then

$$R_{ch}(f(t-a)) = \cosh(pa) F_C(p, (T-a)) + \sinh(pa) F_S(p, (T-a))$$

**Proof:** Let  $R_{sh}(f(t)) = F_S(p, T)$  and  $R_{ch}(f(t)) = F_C(p, T)$ , Then

$$\begin{aligned} R_{ch}(f(t-a)) &= \int_0^T f(t-a) \cosh(pt) dt \\ &= \int_0^{T-a} f(x) \cosh(p(a+x)) dx \\ &= \int_0^{T-a} f(x) [\cosh(pa) \cdot \cosh(px) + \sinh(pa) \cdot \sinh(px)] dx \end{aligned}$$

$$\begin{aligned}
 &= \cosh(pa) \int_0^{T-a} f(x) \cosh(px) dx + \sinh(pa) \int_0^{T-a} f(x) \sin(px) dx \\
 &= \cosh(pa) F_C(p, (T-a)) + \sinh(pa) F_S(p, (T-a))
 \end{aligned}$$

#### 4. EXAMPLES:

##### 4.1 Find $R_{ch}(t \cosh(t))$

**Solution:** We know that

$$R_{ch}(t) = \frac{T \sinh(pT)}{p} - \frac{\cosh(pT) - 1}{p^2}$$

$$\text{and } R_{ch}(\cosh(at).f(t)) = \frac{F_C((p+a), T) + F_C((p-a), T)}{2}$$

$$\Rightarrow R_{ch}(t \cosh(t)) = \frac{\frac{T \cosh((p+1)T)}{(p+1)} - \frac{\cosh((p+1)T) - 1}{(p+1)^2} + \frac{T \cosh((p-1)T)}{(p-1)} - \frac{\cosh((p-1)T) - 1}{(p-1)^2}}{2}$$

##### 4.2 Find $R_{ch}(t \sinh(t))$

**Solution:** We know that

$$R_{sh}(t) = \frac{T \cosh(pT)}{p} - \frac{\sinh(pT)}{p^2}$$

$$\text{and } R_{ch}(\sinh(at).f(t)) = \frac{-F_S((p-a), T) + F_S((p+a), T)}{2}$$

$$\Rightarrow R_{ch}(t \sinh(t)) = \frac{\frac{-T \cosh((p-1)T)}{(p-1)} + \frac{\sinh((p-1)T)}{(p-1)^2} + \frac{T \cosh((p+1)T)}{(p+1)} - \frac{\sinh((p+1)T)}{(p+1)^2}}{2}$$

##### 4.3 Find $R_{ch}(te^t)$

**Solution:** We know that

$$R_{sh}(t) = \frac{T \cosh(pT)}{p} - \frac{\sinh(pT)}{p^2}$$

$$\text{and } R_{ch}(e^{at}.f(t)) = \frac{F_C((p-a), T) + F_C((p+a), T) - F_S((p-a), T) + F_S((p+a), T)}{2}$$

$$\Rightarrow R_{ch}(te^t) = \frac{\frac{T \cosh((p+1)T)}{(p+1)} - \frac{\sinh((p+1)T)}{(p+1)^2} - \frac{T \cosh((p-1)T)}{(p-1)} + \frac{\sinh((p-1)T)}{(p-1)^2} + \frac{T \cosh((p-1)T)}{(p-1)} - \frac{\sinh((p-1)T)}{(p-1)^2} + \frac{T \cosh((p+1)T)}{(p+1)} - \frac{\sinh((p+1)T)}{(p+1)^2}}{2}$$

##### 4.4 Find $R_{ch}(te^{-t})$

**Solution:** We know that

$$R_{sh}(t) = \frac{T \cosh(pT)}{p} - \frac{\sinh(pT)}{p^2}$$

$$\text{and } R_{ch}(e^{-at}.f(t)) = \frac{F_c((p-a),T) + F_c((p+a),T) + F_s((p-a),T) - F_s((p+a),T)}{2}$$

$$\Rightarrow R_{ch}(te^{-t})$$

=

$$\frac{T \cosh((p+1)T) - \frac{\cosh((p+1)T)-1}{(p+1)^2} + T \cosh((p-1)T) - \frac{\cosh((p-1)T)-1}{(p-1)^2} + T \cosh((p-1)T) - \frac{\sinh((p-1)T)}{(p-1)^2} - T \cosh((p+1)T) + \frac{T \sinh((p+1)T)}{(p+1)^2}}{2}$$

#### 4.5 Find $R_{ch}(t \cos(t))$

**Solution:** We know that

$$R_{ch}(t) = \frac{T \sinh(pT)}{p} - \frac{\cosh(pT)-1}{p^2} \quad \text{and } R_{ch}(\cos(at).f(t)) = \frac{F_c((p+ia),T) + F_c((p-ia),T)}{2}$$

$$\Rightarrow R_{ch}(t \cos(t)) = \frac{T \cosh((p+ia)T) - \frac{\cosh((p+ia)T)-1}{(p+ia)^2} + T \cosh((p-ia)T) - \frac{\cosh((p-ia)T)-1}{(p-ia)^2}}{2}$$

#### 4.6 Find $R_{ch}(t \sin(t))$

**Solution:** We know that

$$R_{sh}(t) = \frac{T \cosh(pT)}{p} - \frac{\sinh(pT)}{p^2}$$

$$\text{and } R_{ch}(\sin(at).f(t)) = \frac{-F_s((p-ia),T) + F_s((p+ia),T)}{2i}$$

$$\Rightarrow R_{ch}(t \sin(t)) = \frac{-\frac{T \cosh((p-i)T)}{(p-i)} + \frac{\sinh((p-i)T)}{(p-i)^2} + \frac{T \cosh((p+i)T)}{(p+i)} - \frac{\sinh((p+i)T)}{(p+i)^2}}{2i}$$

#### 4.7 Find $R_{ch}(\sin(5t))$

**Solution:** We know that

$$R_{sh}(\sin(t)) = \left( \frac{-1}{p^2+1} \right) \sin(pT) \cdot \cos(T) + \left( \frac{p}{p^2+1} \right) \cosh(pT) \sin(T) \quad \text{and } R_{sh}(f(at)) = \frac{F_s\left(\frac{p}{a}, aT\right)}{a}$$

$$\Rightarrow R_{sh}(\sin(5t)) = \left( \frac{-5}{p^2+25} \right) \sinh(pT) \cos(5T) + \left( \frac{p}{p^2+25} \right) \cosh(pT) \sin(5T)$$

#### 4.8 Find $R_{ch}(\sin(5t))$

**Solution:** We know that

$$R_{ch}(\sin(t)) = \left( \frac{1}{p^2+1} \right) [1 - \cosh(pT) \cdot \cos(T)] + \left( \frac{p}{p^2+1} \right) \sinh(pT) \sin(T)$$

$$\text{and } R_{\text{ch}}(f(at)) = \frac{F_c\left(\frac{p}{a}, aT\right)}{a}$$

$$\Rightarrow R_{\text{ch}}(\sin(5t)) = \left(\frac{5}{p^2 + 25}\right) [1 - \cosh(pT) \cos(5T)] + \left(\frac{p}{p^2 + 25}\right) \sinh(pT) \sin(5T)$$

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